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4 8 Full file at <https://testbanku.eu/Solution-Manual-for-Control-Systems-Engineering-7th-Edition-by-Nise> 1-14 Chapter 1: Introduction The characteristic polynomial is $M^2 + 4(M + 2i)(M + 2i)$ Thus, the total solution is $x(t) = A \cos(2t) + B \sin(2t) + t^2 + 1 + 4 + 8 + 1 + 9$ Solving for the arbitrary constants, $x(0) = A - = 1$ Therefore, $A = .$

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